# Near-Optimal Algorithms for Piecewise-Stationary Cascading Bandits

#### Lingda Wang

Department of Electrical and Computer Engineering University of Illinois at Urbana-Champaign

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Joint work with Huozhi Zhou (UIUC), Bingcong Li (UMN), Lav R. Varshney (UIUC), and Zhizhen Zhao (UIUC)



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### Motivation

- Cascading bandit (CB) is a variant of multi-armed bandit (MAB) tailored for cascade model (CM) that depicts a user's online behavior. CB can be characterized by *L* different attraction distributions {*f<sub>i</sub>*}<sup>*L*</sup><sub>*i*=1</sub> associated with items (e.g., web pages and ads).
- **Goal of CB**: Identifying the *K* most attractive items to the user and maximizing the number of clicks during the Learning process.

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- **Goal of CB**: Identifying the *K* most attractive items to the user and maximizing the number of clicks during the Learning process.
- What if the attraction distributions are **non-stationary** (e.g. User's preference might change)?



### Learning Protocol of Cascading Bandits

- $CB = (\mathcal{L}, T, \{f_{\ell,t}\}_{\ell \in \mathcal{L}, t \leq T}, K)$ :
  - $\mathcal{L}$ : Ground set containing L items (e.g., web pages or ads);
  - $\{f_{\ell,t}\}_{\ell \in \mathcal{L}, t \leq T}$ : Pmfs of attraction distributions of items in  $\mathcal{L}$ ;
  - T is the time horizon, and K is the number of items recommended by the learner to the user.

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- *T* is the time horizon, and *K* is the number of items recommended by the learner to the user.
- In each time step  $t = 1, 2, \ldots, T$ :
  - Given historical data, the learner selects a *K*-item ranked list  $\mathcal{A}_t := (a_{1,t}, \ldots, a_{K,t}) \in \Pi_K (\mathcal{L})$  to recommend to the user;
  - The learner observes the feedback from the user at time *t*:

$$F_t = \begin{cases} \emptyset, & \text{if no click,} \\ \arg\min_k \{1 \le k \le K : Z_{\mathsf{a}_{k,t},t} = 1\}, & \text{otherwise,} \end{cases}$$

which indicates the first item clicked by the user  $(Z_{a_{k,t},t})$  or no click  $(\emptyset)$ .

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# Piecewise-Stationary Cascading Bandits: Problem Formulation

- Consider Piecewise-Stationary CB (PS-CB) with N segments, where  $N = 1 + \sum_{t=1}^{T-1} \mathbb{I}\{\exists \ell \in \mathcal{L} \text{ s.t. } f_{\ell,t} \neq f_{\ell,t+1}\}.$
- For the *i*th piecewise-stationary segment t ∈ [ν<sub>i-1</sub> + 1, ν<sub>i</sub>], the attraction distribution of item ℓ, denoted as f<sup>i</sup><sub>ℓ</sub>, remains unchanged.

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- Goal: Minimize the expected cumulative regret:

$$\mathcal{R}(T) = \mathbb{E}\left[\sum_{t=1}^{T} R\left(\mathcal{A}_{t}, \mathsf{w}_{t}, \mathsf{Z}_{t}\right)\right],$$

where  $w_t$  is attraction probability vector. Here,  $R(\mathcal{A}_t, w_t, Z_t) = r(\mathcal{A}_t^*, w_t) - r(\mathcal{A}_t, Z_t)$  with  $\mathcal{A}_t^* = \arg \max_{\mathcal{A}_t \in \Pi_K(\mathcal{L})} r(\mathcal{A}_t, w_t)$  being the optimal list that maximizes the expected reward, where  $r(\mathcal{A}_t, w_t) = 1 - \prod_{k=1}^{K} (1 - w_{a_{k,t},t}).$ 

### Contributions

• **Tighter regret bounds.** The proposed two algorithms are shown to have regret bounds  $\mathcal{O}(\sqrt{NLT \log T})$ , which tightens those in *Li* et al. <sup>1</sup> by a factor of  $\sqrt{L}$  and  $\sqrt{L} \log T$ , respectively.

<sup>&</sup>lt;sup>1</sup>Chang Li and Maarten de Rijke, "Cascading non-stationary bandits: Online learning to rank in the non-stationary cascade model," in Proc. 28th Int. Joint Conf. Artif. Intell. (IJCAI 2019), 2019, pp. 2859–2865.

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- Matching lower bound. We establish that the minimax regret lower bound for PS-CB is  $\Omega(\sqrt{NLT})$ . Such a lower bound: i) implies the proposed algorithms are optimal up to a logarithm factor; ii) is the first to characterize dependence on N, L, and T for PS-CB.

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- Better numerical peformance. Numerical experiments on a real-world benchmark dataset reveal the merits of proposed algorithms over state-of-the-art approaches.

### The Proposed Algorithms

- GLRT-CascadeUCB and GLRT-CascadeKL-UCB algorithms run in three phases:
  - For *p* fraction of the time, the algorithms select *K* items by uniform sampling. For the rest of the time, the algorithms select *K* items with highest UCB/KL-UCB indices;
  - Update the statistics of K selected items:

$$\mathsf{UCB}(\ell) = \hat{\mathsf{w}}(\ell) + \sqrt{\frac{3\log(t- au)}{2n_\ell}},$$
  
 $\mathsf{JCB}_{\mathsf{KL}}(\ell) = \max\{q \in [\hat{\mathsf{w}}(\ell), 1] : n_\ell imes \mathsf{KL}(\hat{\mathsf{w}}(\ell), q) \le g(t- au)\}$ 

• At the end of each round, run GLRT change-point detector <sup>2</sup> on selected items at this round. If at least one item's click probability has changed, restart the UCB indices/KL-UCB indices of all items.

<sup>&</sup>lt;sup>2</sup>Lilian Besson and Emilie Kaufmann, "The generalized likelihood ratio test meets klucb: an improved algorithm for piecewise non-stationary bandits," arXiv preprintarXiv:1902.01575, 2019.

#### Theoretical Analysis: Regret Upper Bounds

#### Theorem (Wang et al. 2019, GLRT-CascadeUCB)

Under mild assumptions, GLRT-CascadeUCB guarantees

$$\mathcal{R}(T) \leq \sum_{i=1}^{N} \widetilde{C}_{i} + Tp + \sum_{i=1}^{N-1} d_{i} + 3NTL\delta,$$
  
where  $\widetilde{C}_{i} = \sum_{\ell=K+1}^{L} \frac{12}{\Delta_{s_{i}(\ell),s_{i}(K)}^{i}} \log T + \frac{\pi^{2}}{3}L.$ 

#### Corollary (Wang et al. 2019, GLRT-CascadeUCB)

The regret of GLRT-CascadeUCB is established by choosing  $\delta = 1/T$  and  $p = \sqrt{NL \log T/T}$ :

$$\mathcal{R}(T) = \mathcal{O}\left(\frac{N(L-K)\log T}{\Delta_{\text{opt}}^{\min}} + \frac{\sqrt{NLT\log T}}{\left(\Delta_{\text{change}}^{\min}\right)^2}\right)$$

# Theoretical Analysis: Regret Upper Bounds

#### Theorem (Wang et al. 2019, GLRT-CascadeKL-UCB)

# Under mild assumptions, GLRT-CascadeKL-UCB guarantees $\mathcal{R}(T) \leq T(N-1)(L+1)\delta + Tp$ $+ \sum_{i=1}^{N-1} d_i + NK \log \log T + \sum_{i=0}^{N-1} \widetilde{D}_i,$

where  $D_i$  is a term depending on log T and the suboptimal gaps.

#### Corollary (Wang et al. 2019, GLRT-CascadeKL-UCB)

Choosing the same  $\delta$  and p as GLRT-CascadeUCB, GLRT-CascadeKL-UCB has the same regret as GLRT-CascadeUCB.

As *T* becomes larger, the regret is dominated by the cost of the change-point detection component, implying the regret is *O*(√*NLT* log *T*).

#### Theorem (Wang et al. 2019, Lower Bound)

If  $L \ge 3$  and  $T \ge MN\frac{(L-1)^2}{L}$ , then for any policy, the worst-case regret is at least  $\Omega(\sqrt{NLT})$ , where  $M = 1/\log \frac{4}{3}$ , and  $\Omega(\cdot)$  notation hides a constant factor that is independent of N, L, and T.

 This lower bound is the first characterization involving N, L, and T. And it indicates our proposed algorithms are nearly order-optimal within a logarithm factor \sqrt{log T}.

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	Regret	Diff
Lower Bound	$\mathcal{O}(\sqrt{NLT})$	0
CascadeDUCB <sup>3</sup>	$\mathcal{O}(L\sqrt{NT}\log T)$	$\mathcal{O}(\sqrt{L}\log T)$
CascadeSWUCB <sup>3</sup>	$\mathcal{O}(L\sqrt{NT\log T})$	$\mathcal{O}(\sqrt{L\log T})$
GLRT-CascadeUCB	$\mathcal{O}\left(\sqrt{NLT\log T}\right)$	$\mathcal{O}(\sqrt{\log T})$
GLRT-CascadeKL-UCB	$\mathcal{O}\left(\sqrt{NLT\log T}\right)$	$\mathcal{O}(\sqrt{\log T})$

<sup>&</sup>lt;sup>3</sup>Chang Li and Maarten de Rijke, "Cascading non-stationary bandits: Online learning to rank in the non-stationary cascade model," in Proc. 28th Int. Joint Conf. Artif. Intell. (IJCAI 2019), 2019, pp. 2859–2865.  $\rightarrow \bigcirc$ 

#### Numerical Results



- Experiment settings:
  - Use the Yahoo! benchmark dataset<sup>4</sup>;
  - Pre-process the dataset by adopting the same method as *Cao et al.*<sup>5</sup>, where L = 6, K = 2, N = 9, and T = 90000.

<sup>&</sup>lt;sup>4</sup>https://webscope.sandbox.yahoo.com

# Thank You!

• Full version of Nearly Optimal Algorithms for Piecewise-Stationary Cascading Bandits is available online at: https://arxiv.org/abs/1909.05886.

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